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Claims

1. Control method for an actuator (1-4) of an injector of a fuel injection system for an internal combustion engine, which method has the following steps:

- specifying a target value ( $SOI_{SOIL}$ ) for the start of injection, and
- electrically controlling the actuator (1-4) at a specific trigger time ( $t_{TRIGGER}$ ) with a specific actuator energy (E),  
c h a r a c t e r i z e d   b y  
the following steps:
  - detecting an actual value ( $SOI1_{IST}$ ,  $SOI2_{IST}$ ,  $SOI3_{IST}$ ,  $SOI4_{IST}$ ) at the start of injection,
  - determining a deviation ( $\Delta SOI1$ ,  $\Delta SOI2$ ,  $\Delta SOI3$ ,  $\Delta SOI4$ ) between the target and actual values at the start of injection, and
  - setting the actuator energy (E) as a function of the deviation ( $\Delta SOI1$ ,  $\Delta SOI2$ ,  $\Delta SOI3$ ,  $\Delta SOI4$ ) between the target and actual values at the start of injection for controlling the start of said injection.

2. Control method according to claim 1  
c h a r a c t e r i z e d   i n   t h a t  
controlling takes place jointly for a plurality of actuators (1-4) by setting the actuator energy (E) jointly for a plurality of actuators (1-4).

3. Control method according to claim 2  
c h a r a c t e r i z e d   b y  
the following steps:

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- detecting the actual value ( $SOI1_{IST}$ ,  $SOI2_{IST}$ ,  $SOI3_{IST}$ ,  $SOI4_{IST}$ ) at the start of injection separately for the individual actuators (1-4),
- determining the deviation ( $\Delta SOI1$ ,  $\Delta SOI2$ ,  $\Delta SOI3$ ,  $\Delta SOI4$ ) between the target and actual values at the start of injection separately for the individual actuators (1-4),
- determining the mean deviation ( $\Delta SOI$ ) between the target and actual values at the start of injection for a plurality of actuators (1-4), and
- setting the actuator energy (E) jointly for a plurality of actuators (1-4) according to the mean deviation ( $\Delta SOI$ ) between the target and actual values at the start of injection.

4. Control method according to claim 1  
c h a r a c t e r i z e d i n t h a t  
controlling takes place individually for in each case one of a plurality of actuators (1-4), with the actuator energy (E) being set in each case on an actuator-specific basis.

5. Control method according to claim 4  
c h a r a c t e r i z e d b y  
the following steps:

- detecting the actual value ( $SOI1_{IST}$ ,  $SOI2_{IST}$ ,  $SOI3_{IST}$ ,  $SOI4_{IST}$ ) at the start of injection separately for the individual actuators (1-4),
- determining the deviation ( $\Delta SOI1$ ,  $\Delta SOI2$ ,  $\Delta SOI3$ ,  $\Delta SOI4$ ) between the target and actual values at the start of injection separately for the individual actuators (1-4), and
- setting the actuator energy (E) separately for the individual actuators (1-4) as a function of the respective

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actuator-specific deviation ( $\Delta SOI1$ ,  $\Delta SOI2$ ,  $\Delta SOI3$ ,  $\Delta SOI4$ ) between the target and actual values at the start of injection.

6. Control method according to one of the preceding claims characterized in that the trigger time ( $t_{TRIGGER}$ ) for controlling the actuators (1-4) is set independently of the deviation ( $\Delta SOI1$ ,  $\Delta SOI2$ ,  $\Delta SOI3$ ,  $\Delta SOI4$ ) between the target and actual values at the start of injection.

7. Control method according to one of claims 1 to 5 characterized in that as part of controlling and in addition to setting the actuator energy (E), the trigger time ( $t_{TRIGGER}$ ) is also set as a function of the deviation ( $\Delta SOI1$ ,  $\Delta SOI2$ ,  $\Delta SOI3$ ,  $\Delta SOI4$ ) between the target and actual values at the start of injection for controlling said start of injection.

8. Control method according to claim 7 characterized in that the actuator energy (E) is set jointly for a plurality of actuators (1-4) while the trigger time is set separately for the individual actuators (1-4).

9. Control method according to one of the preceding claims characterized in that the actual value ( $SOI1_{IST}$ ,  $SOI2_{IST}$ ,  $SOI3_{IST}$ ,  $SOI4_{IST}$ ) at the start of injection is detected by means of a seat contact switch (6-9), with said seat contact switch (6-9) detecting a valve needle position of the injector.

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10. Control method according to one of the preceding claims characterized in that the actuator energy (E) is set within the scope of controlling on a discrete time and/or on a discrete value basis.

11. Control device for an actuator (1-4) of an injector for a fuel injection system of an internal combustion engine, which device has

- a controlling element (5, 5.1-5.4) for electrically controlling the actuator (1-4) at a specific trigger time ( $t_{\text{TRIGGER}}$ ) with a specific actuator energy (E) characterized by
- a measuring device (6-10) for detecting an actual value ( $\text{SOI1}_{\text{IST}}$ ,  $\text{SOI2}_{\text{IST}}$ ,  $\text{SOI3}_{\text{IST}}$ ,  $\text{SOI4}_{\text{IST}}$ ) at the start of injection,
- a first controller (16, 16.1-16.4) for setting the actuator energy (E) as a function of a deviation ( $\Delta\text{SOI1}$ ,  $\Delta\text{SOI2}$ ,  $\Delta\text{SOI3}$ ,  $\Delta\text{SOI4}$ ) between the measured actual value ( $\text{SOI1}_{\text{IST}}$ ,  $\text{SOI2}_{\text{IST}}$ ,  $\text{SOI3}_{\text{IST}}$ ,  $\text{SOI4}_{\text{IST}}$ ) at the start of injection and a pre-specified target value ( $\text{SOI}_{\text{SOLL}}$ ) at the start of injection.

12. Control device according to claim 11 characterized in that the actuator energy (E) can be set jointly within the scope of controlling for a plurality of actuators (1-4).

13. Control device according to claim 12 characterized by a computing unit (15) for calculating a mean value ( $\Delta\text{SOI}$ ) of the deviation ( $\Delta\text{SOI1}$ ,  $\Delta\text{SOI2}$ ,  $\Delta\text{SOI3}$ ,  $\Delta\text{SOI4}$ ) between the target and actual values at the start of injection for a plurality of actuators (1-4), with the first controller (16) setting the

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actuator energy (E) for a plurality of actuators (1-4) in keeping with the mean value ( $\Delta SOI$ ).

14. Control device according to claim 11  
c h a r a c t e r i z e d i n t h a t  
the actuator energy (E) can be set individually within the scope of controlling for a plurality of actuators (1-4).

15. Control device according to one of claims 11 to 14  
c h a r a c t e r i z e d b y  
a second controller (18) for setting the trigger time ( $t_{\text{TRIGGER}}$ ) for controlling the actuator (1-4) as a function of the deviation ( $\Delta SOI1$ ,  $\Delta SOI2$ ,  $\Delta SOI3$ ,  $\Delta SOI4$ ) between the measured actual value ( $SOI1_{\text{IST}}$ ,  $SOI2_{\text{IST}}$ ,  $SOI3_{\text{IST}}$ ,  $SOI4_{\text{IST}}$ ) at the start of injection and the pre-specified target value ( $SOI_{\text{SOLL}}$ ) at the start of injection.

16. Control device according to one of claims 11 to 15  
c h a r a c t e r i z e d i n t h a t  
the measuring device (6-10) has a seat contact switch 69) which detects a valve needle position of the injector.